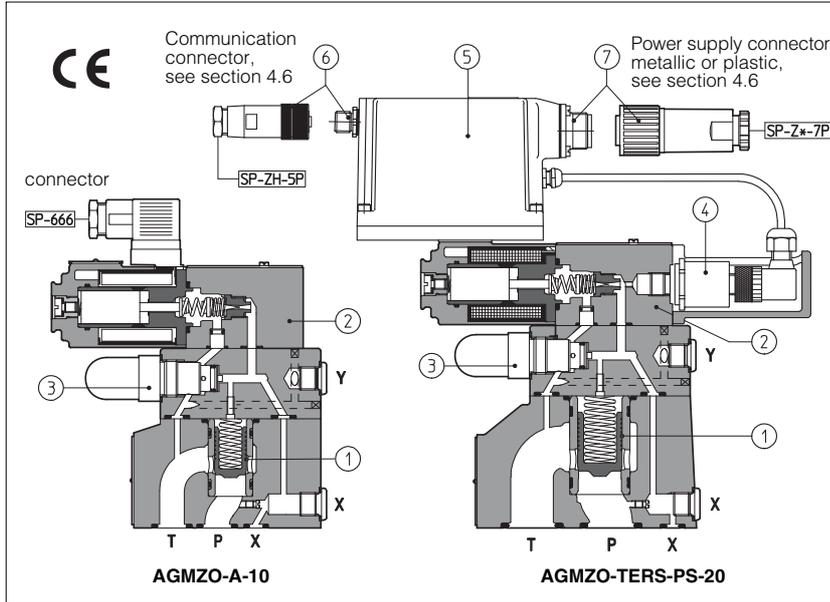


# Proportional relief valves type AGMZO

two stage, ISO 6264 size 10, 20 and 32



AGMZO are poppet type proportional pressure relief valves, pilot operated with pressure regulation proportional to electronic reference signal.

They operate in association with electronic drivers, see table 8, which supply the proportional valve with proper current to align valve regulation to the reference signal supplied to the electronic driver.

They are available in different executions:

- -A, without integral pressure transducer.
- -AE, -AES, as -A plus analogue (AE) or digital (AES) integral electronics 5.
- -TERS with integral pressure transducer 4 plus digital electronics 5 preset in closed loop, featuring improved static and dynamic performances.
- -AERS as -TERS but without integral pressure transducer (predisposed for connection of remote pressure transducer).

The piloting pressure to the poppet 1 is modulated by a proportional relief valve type RZMO 2, see table F007.

The pilot relief valve 3 with manual adjustment is installed to limit the max pressure value.

The integral electronics ensures factory presetting, fine functionality plus valve-to-valve interchangeability and simplified wiring and installation.

Following communication interfaces 6 are available for the digital -AES, -TERS and -AERS executions:

- -PS, RS232 serial communication interface. The valve reference signal is provided with analogue commands via the 7 (or 12) pins connector 7.
  - -BC, CANbus interface
  - -BP, PROFIBUS-DP interface
- In the -BC and -BP interfaces the valve reference signal is provided via fieldbus; during start up or maintenance, the valves can be operated with analogue signals via the 7 (or 12) pins connector 7.

The coils are fully plastic encapsulated (insulation class H), and the valves have antivibration, antishock and weather-proof features.

Surface mounting: ISO 6264 size 10, 20 and 32.  
Max flow: 200, 400, 600 l/min  
Max pressure: 315 bar.

## 1 MODEL CODE

**AGMZO - TERS - PS - 10 / 315 / \* \*\* / \***

Proportional relief valves

- A** = without integral transducer
- AE** = as A plus integral electronics
- AES** = as A plus integral digital electronics
- TERS** = with integral digital electronics and pressure transducer
- AERS** = as TERS but with remote pressure transducer (to be ordered separately, see tab. G460)

Communication interfaces (only for AES, TERS and AERS)  
**PS** = RS232 serial  
**BC** = CANbus  
**BP** = PROFIBUS-DP

Size:  
**10, 20, 32**

Pressure range:  
**50** = 50 bar (not for -TERS and -AERS)      **210** = 210 bar  
**100** = 100 bar      **315** = 315 bar

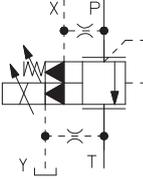
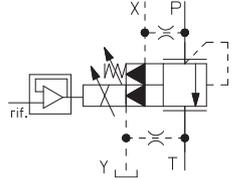
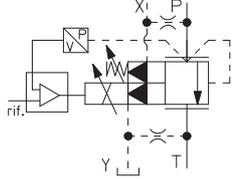
Synthetic fluids  
**WG** = water-glycol  
**PE** = phosphate ester

Series number

Options, see section 4:

- E** = external pilot
- Y** = external drain
- for -A execution:**
- 6** = with 6 V<sub>DC</sub> coil instead of standard 12V<sub>DC</sub> coil
- 18** = with 18 V<sub>DC</sub> coil instead of standard 12V<sub>DC</sub> coil
- for -AE execution:**
- I** = current reference (4±20 mA)
- Q** = enable signal
- for -AES, -TERS and -AERS executions:**
- I** = current reference 4±20 mA (only for TERS execution)
- Z** = double power supply, enable and fault (12 pin connector)
- C** = remote pressure transducer with current feedback 4±20 mA (only for AERS execution)

## 2 HYDRAULIC CHARACTERISTICS (based on mineral oil ISO VG 46 at 50 °C)

Hydraulic symbols									
	AGMZO-A			AGMZO-AE, AGMZO-AES			AGMZO-TERS, AGMZO-AERS		
Valve model	AGMZO-A			AGMZO-AE, AGMZO-AES			AGMZO-TERS, AGMZO-AERS		
Size	10	20	32	10	20	32	10	20	32
Max regulated pressure [bar]	50; 100; 210; 315			100; 210; 315					
Min. regulated pressure (Q = 25 l/min) [bar]	7	6	5,5	7	6	5,5			
Max pressure at port P [bar]				315					
Max pressure at port T [bar]				210					
Max flow [l/min]	200	400	600	200	400	600			
Response time 0 - 100% step signal (depending on installation) - see section 6.4 [ms]	120	135	150	80	100	115			
Hysteresis [% of the max pressure]				≤ 2			≤ 0,5		
Linearity [% of the max pressure]				≤ 3			≤ 1,0		
Repeatability [% of the max pressure]				≤ 2			≤ 0,2		
Thermal drift (-TERS execution)				zero point displacement < 1% at ΔT = 40°C					

Above performance data refer to valves coupled with Atos electronic drivers, see section 8.

### 3 MAIN CHARACTERISTICS OF PROPORTIONAL PRESSURE RELIEF VALVES TYPE AGMZ0

Assembly position	Any position
Subplate surface finishing	Roughness index, $\sqrt{Ra}$ flatness ratio 0,01/100 (ISO 1101)
Ambient temperature	-20°C ÷ +70°C for -A execution; -20°C ÷ +60°C for -AE and -AES; -20°C ÷ +50°C for -TERS and -AERS
Fluid	Hydraulic oil as per DIN 51524 ... 535 for other fluids see section 1
Recommended viscosity	15 ÷ 100 mm <sup>2</sup> /s at 40°C (ISO VG 15÷100)
Fluid contamination class	ISO 18/15 achieved with in line filters of 10 µm and $\beta_{10} \geq 75$ (recommended)
Fluid temperature	-20°C +60°C (standard and /WG seals) -20°C +80°C (/PE seals)

#### 3.1 Electrical characteristics

Coil resistance R at 20°C	3 ÷ 3,3 Ω for standard 12 V <sub>DC</sub> coil; 2 ÷ 2,2 Ω for 6 V <sub>DC</sub> coil; 13 ÷ 13,4 Ω for 18 V <sub>DC</sub> coil
Max solenoid current	2,6 A for standard 12 V <sub>DC</sub> coil; 3,25 A for 6 V <sub>DC</sub> coil; 1,5 A for 18 V <sub>DC</sub> coil
Max power	40 Watt
Protection degree (CEI EN-60529)	IP65 for -A execution; IP65÷67 for -AE, -TERS and AERS executions, depending to the connector type (see sect. 4.6)
Duty factor	Continuous rating (ED=100%)

### 4 INTEGRAL ELECTRONICS OPTIONS AND WIRING

#### 4.1 Option /I

It provides the 4÷20 mA current reference signal and the current monitor signal instead of the standard 0÷10 V. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise. In case of breakage of the reference signal cable, the valve functioning is disabled.

#### 4.2 Option /Q

Safety option providing the possibility to enable or disable the valve functioning without cutting the power supply.

#### 4.3 Option /Z

Safety option, specifically introduced for -BC and -BP communication interfaces, provides two separated electric power supplies for the digital electronic circuits and for the solenoid power supply stage. The Enable and Fault signals are also available. The option /Z allows to interrupt the valve functioning by cutting the solenoid power supply (e.g. for emergency, as provided by the European Norms EN954-1 for components with safety class 2), but keeping energized the digital electronic circuits, thus avoiding fault conditions of the machine fieldbus controller.

For the electrical wiring, see tab. G115 and G205.

#### 4.4 Option /C

The valve electronics is set to receive the 4÷20 mA feedback signal from the remote pressure transducer, instead of the standard 0÷10 V.

#### 4.5 Integral electronics wiring

For the electric wiring shielded cables must be provided: the shield must be connected to the power supply zero **on the generator side**, see tab. **F003**

POWER SUPPLY CONNECTOR				
PIN	SIGNAL DESCRIPTION	-AE, -AES, -TERS, -AERS	-AE/I, -TERS/I, -AERS/I	-AE/Q
A	Power supply 24 V <sub>DC</sub>	Stabilized: +24V <sub>DC</sub>		
B	Power supply zero	Filtered and rectified: V <sub>rms</sub> = 21 ÷ 33 (ripple max 2V <sub>pp</sub> )		
C	Signal zero	Reference 0 V <sub>DC</sub>	Reference 0 V <sub>DC</sub>	Enabling input normal working 9 ÷ 24 V <sub>DC</sub>
D	Input signal +	0 ÷ 10 V <sub>DC</sub>	4 ÷ 20 mA	0 ÷ 10 V
E	Input signal -			
F	Monitor driving current (for -AE, -AES) regulated pressure (for -TERS, -AERS)	0 ÷ 10 V referred to pin C (signal 0 V <sub>DC</sub> ) 1V = 1A 1V = 10% of regulated pressure	0 ÷ 5 V (-AES/I) 4 ÷ 20 mA (-TERS/I) 1V = 1A 4 ÷ 20 mA = 0÷100% of regulated pressure	0 ÷ 5 V referred to pin B (signal 0 V <sub>DC</sub> ) 1V = 1A -
G	Earth	Connect only when the power supply is not conform to VDE 0551 (CEI 14/6)		

COMMUNICATION INTERFACE CONNECTORS (-AES, -TERS, -AERS)				
Communication options	-PS (RS232) male connector	-BC (CAN Bus) male connector	-BP (PROFIBUS-DP) female connector (reverse key)	
Pin number Signal description	1	NC Not Connected	CAN_SHLD Shield	+5V Termination voltage
	2	NC Not Connected	NC Not Connected	LINE -A Bus line (high)
	3	RS_GND Signal zero data line	CAN_GND Signal zero data line	DGND Signal zero data line / termination voltage
	4	RS_RX Valves receiving data line	CAN_H Bus line (high)	LINE-B Bus line (low)
	5	RS_TX Valves transmitting data line	CAN_L Bus line (low)	SHIELD Shield

PRESSURE TRANSDUCER CONNECTOR (-AERS) see section 7		
PIN	standard version	option /C
1	Pressure signal	Pressure signal
2	Reserved (do not connect)	Reserved (do not connect)
3	Power supply	Power supply
4	GND	Reserved (do not connect)

#### Note:

- electrical signals (e.g. feedback signals) processed by valve electronics must not be used to switch off the machine safety functions. This is in accordance with the European standards (Safety requirements of fluid technology systems and components - hydraulics, EN 982).
- installation notes with basic information for commissioning and start-up are always supplied with the relevant components, together with the specific technical tables.

#### 4.6 Model codes of power supply and communication connectors

VALVE VERSION	-A	-AE, -AES, -TERS, -AERS		-AES/Z, -TERS/Z, -AERS/Z	-RS232 (-PS) OR CANBUS (-BC)	PROFIBUS (-BP)	PRESSURE TRANSDUCER only for AERS
CONNECTOR CODE	SP-666	SP-ZH-7P (1)	SP-ZM-7P (1)	SP-ZH-12P (1)	SP-ZH-5P (1)	SP-ZH-5P/BP (1)	SP-ZH-4P-M8/5 (1)(2)
PROTECTION DEGREE	IP65	IP67	IP67	IP65	IP67	IP67	IP67

(1) to be ordered separately (2) M8 connector moulded on cable 5 mt lenght

### 5 PROGRAMMING DEVICES

The functional parameters of the digital valves, as the bias, scale, ramp and linearization of the regulation characteristic, can be easily set and optimized with graphic interface by using the following software programming devices suitable for standard PC:

**KIT-E-SW-PS** for electronics with RS232 interface (option **-PS**)

**KIT-E-SW-PS-TERS** only for -TERS-PS electronics - simplified version of KIT-E-SW-PS with only bias and scale settings.

**KIT-E-SW-PS-TERS/U** as KIT-E-SW-PS-TERS with serial to USB interface.

**KIT-E-SW-BC** for electronics with CANbus interface (option **-BC**)

**KIT-E-SW-BP** for electronics with PROFIBUS-DP interface (option **-BP**)

see tab. G500 for complete information about the programming device kits and for the PC minimum requirements.

Only for the -BC and -BP communication options, the functional parameters can be alternatively set via fieldbus through the machine control unit, using the standard communication protocol implemented by Atos.

The protocol operating instructions to be implemented in the standard protocols (DS301V4.02, DSP408 for CANbus and DPVO for PROFIBUS-DP) are described in the user manuals MAN-S-BC (for -BC option) and MAN-S-BP (for -BP option) supplied with the relevant programming device kits.

**The above programming devices have to be ordered separately.**

**6 DIAGRAMS** (based on mineral oil ISO VG 46 at 50 °C)

**6.1 Regulation diagrams**

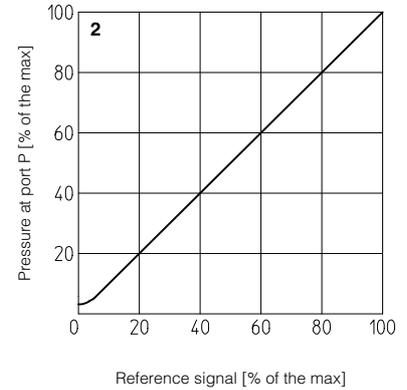
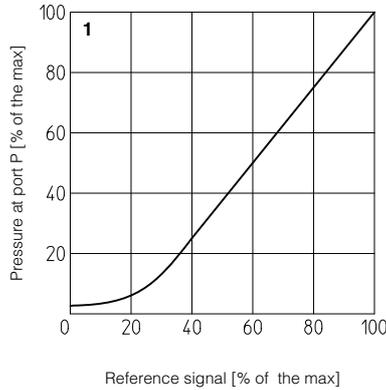
with flow rate Q = 50 l/min

**1** = AGMZO-A, AGMZO-AE, AGMZO-AES

**2** = AGMZO-TERS, AGMZO-AERS

**Notes:**

- 1) For the valves with digital electronics the regulation characteristic can be modified by setting the internal software parameters, see tab. G500.
- 2) For executions -A, -AE and -AES the presence of counter pressure at port T can alter the effective pressure regulation.

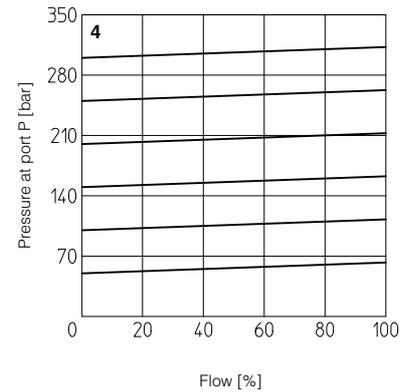
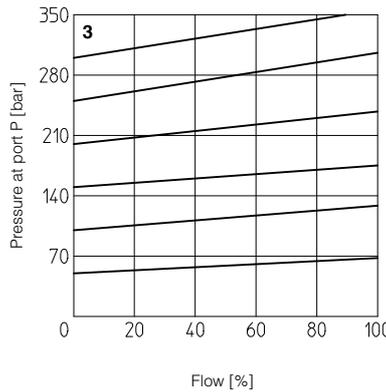


**6.2 Pressure/flow diagrams**

with reference pressure set at Q = 50 l/min

**3** = AGMZO-A, AGMZO-AE, AGMZO-AES

**4** = AGMZO-TER, AGMZO-AERS



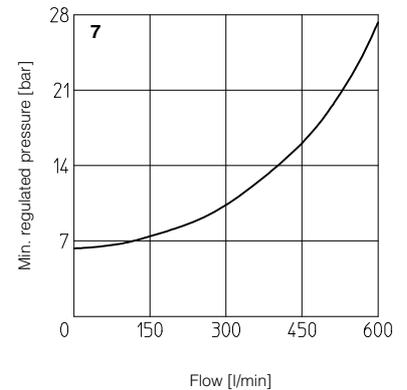
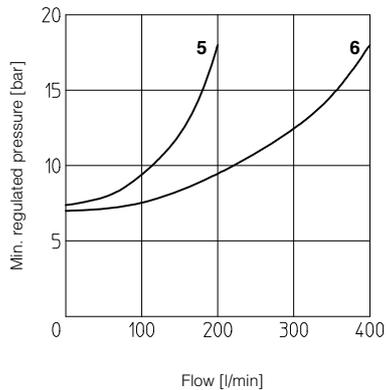
**6.3 Min. pressure/flow diagrams**

with reference signal "null"

**5** = AGMZO-\*-10

**6** = AGMZO-\*-20

**7** = AGMZO-\*-32

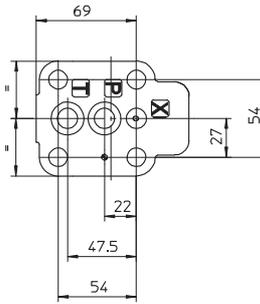


**6.4 Dynamic response**

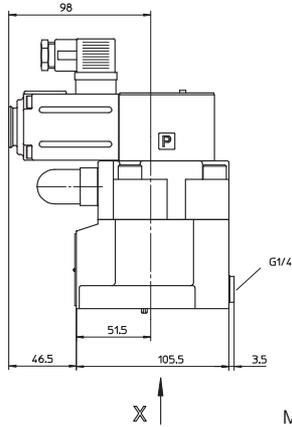
The response times in section 2 have to be considered as average values.

The integral closed loop control of -TERS and -AERS valves is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, the better are the performances. The valves dynamic performances can be optimized depending on the stiffness characteristics of the hydraulic circuit, by setting the internal software parameters. This regulation is particularly helpful in case of circuits with accumulators and/or with great fluid volumes and/or with long hoses.

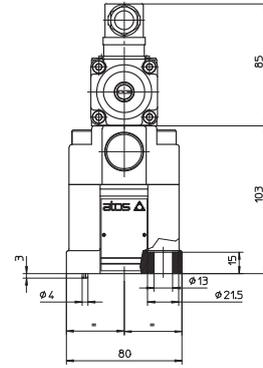
**ISO 6264: 2007**  
**Mounting surface: 6264-06-09-0-97**  
 Fastening bolts: 4 socket head screws  
 M12x35 class 12.9  
 Tightening torque = 125 Nm  
 Seals: 2 OR 123, 1 OR 109/70  
 Ports P, T:  $\varnothing = 14$  mm  
 Port X:  $\varnothing = 3,2$  mm



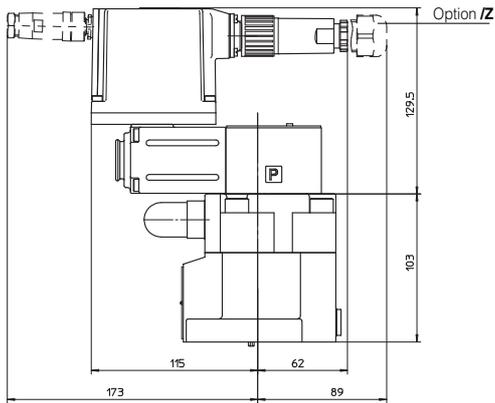
**AGMZO-A-10**



Mass: 6,1 Kg

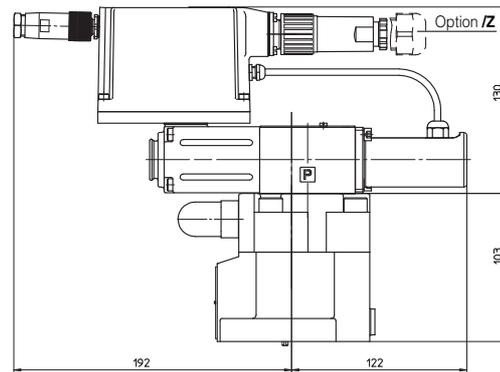


**AGMZO-AE-10 (-AES-\* dotted line)**



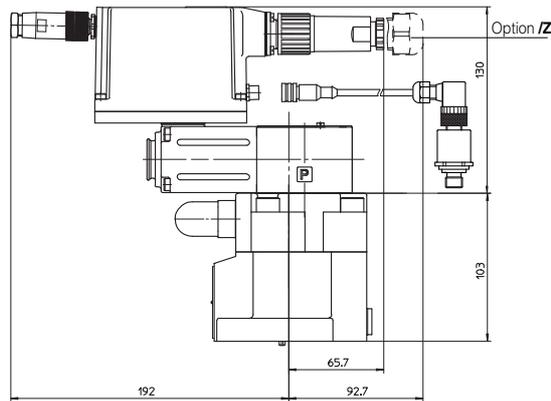
Mass: 6,7 Kg

**AGMZO-TERS-10**



Mass: 7 Kg

**AGMZO-AERS-10**



Mass: 6,8 Kg

ISO 6264: 2007

Mounting surface: 6264-08-13-0-97

Fastening bolts: 4 socket head screws

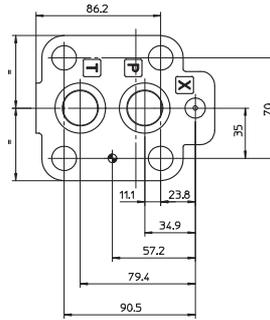
M16x50 class 12.9

Tightening torque = 300 Nm

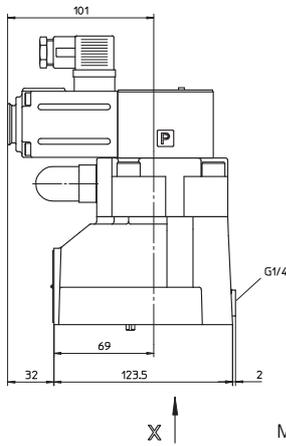
Seals: 2 OR 4112, 1 OR 109/70

Ports P, T: Ø = 24 mm

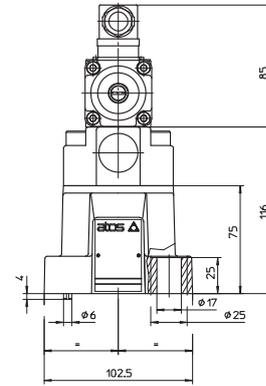
Port X: Ø = 3,2 mm



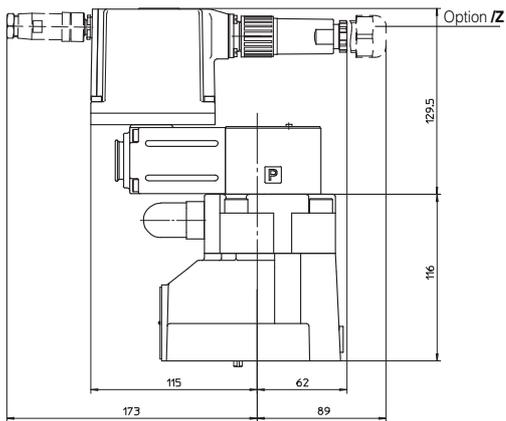
**AGMZO-A-20**



Mass: 9,7 Kg

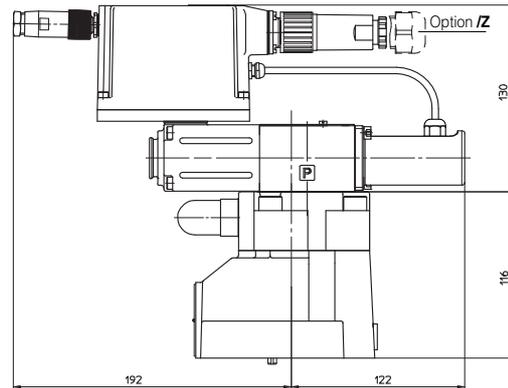


**AGMZO-AE-20** (-AES-\* dotted line)



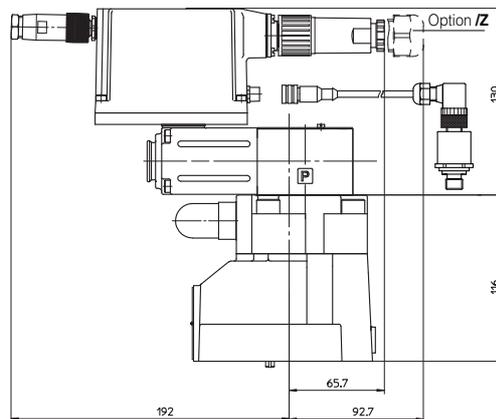
Mass: 10,3 Kg

**AGMZO-TERS-20**



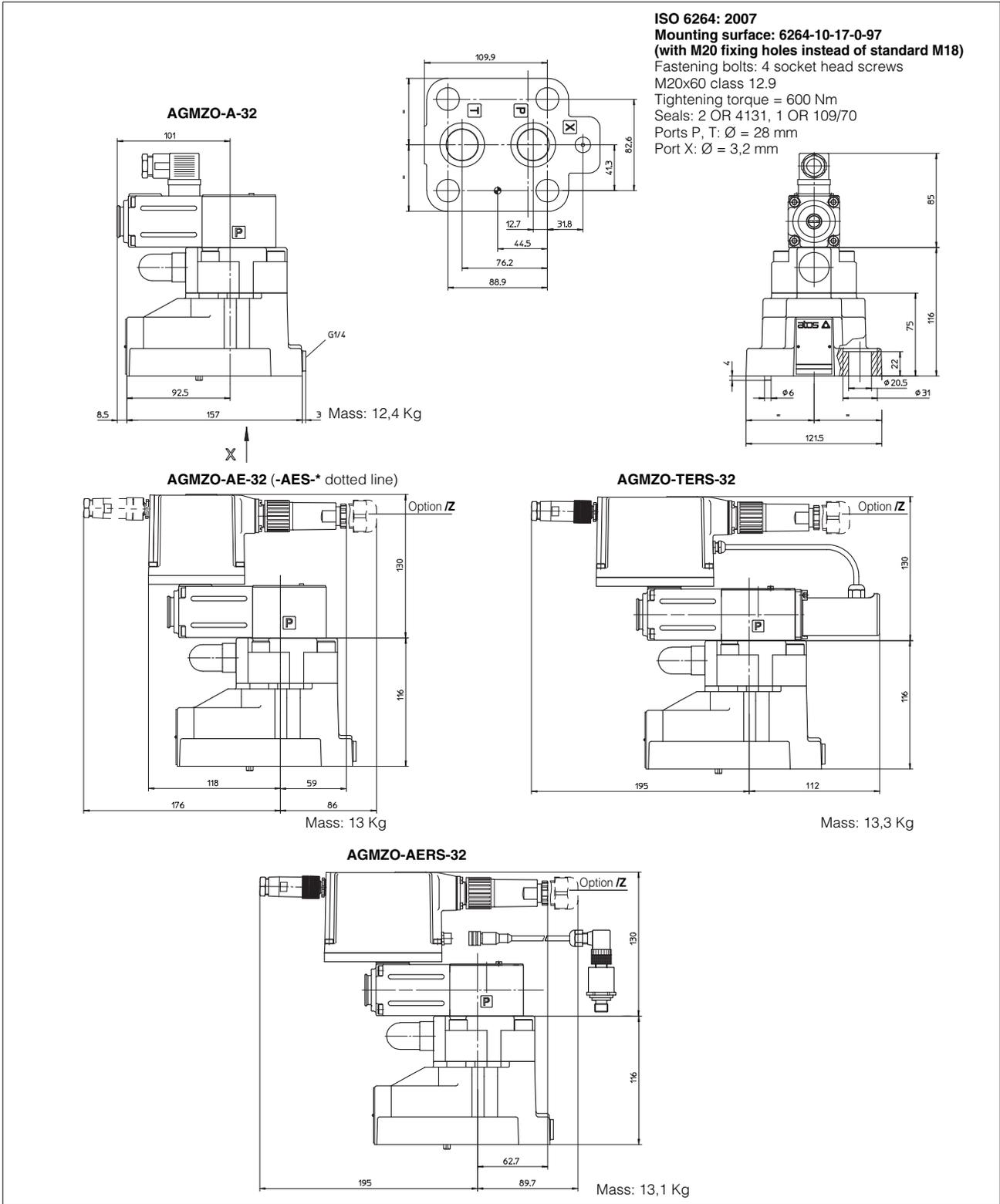
Mass: 10,6 Kg

**AGMZO-AERS-20**



Mass: 10,4 Kg

9 INSTALLATION DIMENSIONS of AGMZO-\* -32 [mm]



10 ELECTRONIC DRIVERS FOR AGMZO

Valve model	-A				-AE	-AES	-TERS	-AERS
Drivers model	E-MI-AC-01F	E-BM-AC-01F	E-ME-AC-01F	E-RP-AC-01F	E-RI-AE	E-RI-AES	E-RI-TERS	E-RI-AERS
Data sheet	G010	G025	G035	G100	G110	G115	G205	

For complete information about the drivers characteristics and relevant options, see the technical data sheet specified in the table.

11 MOUNTING PLATES

Size	Model	Ports location	Gas ports			Ø Counterbore [mm]			Mass [kg]
			P	T	X	P	T	X	
10	BA-306	Attachments P, T, X underneath	1/2"	3/4"	1/4"	30	36,5	21,5	1,5
20	BA-406	Attachments P, T, X underneath	3/4"	3/4"	1/4"	36,5	36,5	21,5	3,5
	BA-506	Attachments P, T, X underneath	1"	1"	1/4"	46	46	21,5	3,5
32	BA-706	Attachments P, T, X underneath	1 1/2"	1 1/2"	1/4"	63,5	63,5	21,5	6

The subplates are supplied with fastening bolts. For further details see table K280