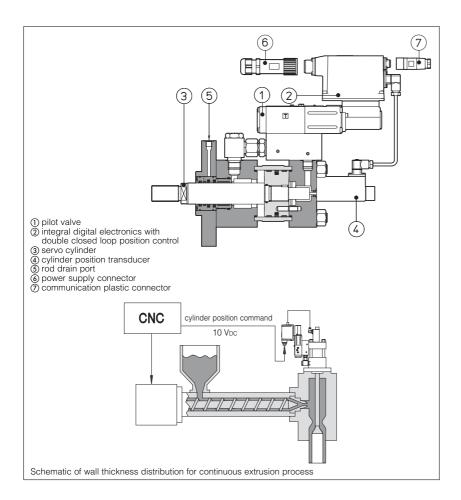


Digital servoactuators for PARISON controls

in blow molding machines



Description:

The Parison control is a well known process used in the plastic blow molding machines for the wall thickness distribution of conti-

It is mainly used to obtain hollow items, as plastic bottles, tanks, etc, whose thickness can be modulated depending to the required localized mechanical resistance. The wall thickness is realized by means of a specific servoactuator operated in position closed loop control (see below the application

The Atos servoactuators CKZ are special proportional servo cylinders with digital integral position control, providing high performances and high regulation repeatability.

The integral and compact execution ensures the best stiffness of the hydraulic system and it permits high dynamics and position accuracy.

Characteristics:

- The digital servoactuator is composed by:
 Special cylinder equipped with low friction seals and with LVDT position transducer. The rod end is threaded for the connection to the extrusion head.
- High dynamic proportional valve with zero
- Ingir dynamic proportional varve with Zero lapped spool and LVDT position transducer.
 Digital integral electronics with double position closed loop control of pilot valve and of cylinder rod. The RS232 serial communication interface permits to optimize the projections performance medicine. the application's performances, modifying via software, the internal parameters by means of the relevant programming device KIT-E-SW-PS to be used with standard PC.

The servoactuator is operated by means of analog commands sent to the 7 or 12 pins power supply connector.
The command signal 0÷10 Vpc defines the

servocylinder rod position in the stroke range 0-12 mm.

The default condition is 0 VDC = rod position fully in; 10 VDC = rod position 12 mm.

Available sizes: ø63/28, ø80/36, ø100/45, ø125/45 ø160/70, ø200/90 mm.



060810 CKZ - X - NN - 1 Mounting flange with threaded holes Servoactuator type: **CKZ** = ISO 6020-2 Control type: **X** = position/speed Position/speed transducer type: $\mathbf{L} = \text{LVDT}$ No pressure/force control and no pressure/force transducer Proportional valve size: 1 = size 06

2 = size 10

Subplate type: 0 = standard

80/36 *0012 - A - PS / GP Rod position vs. position signal: = fully in at 0 VDC **B** = fully out at 0 VDC Power supply connector = 7 pin = 12 pin Parison control RS232 serial communication interface Front flange attachment Stroke = 12 mm

Piston/rod size [mm] (1)

80/36 100/45 125/45 160/70

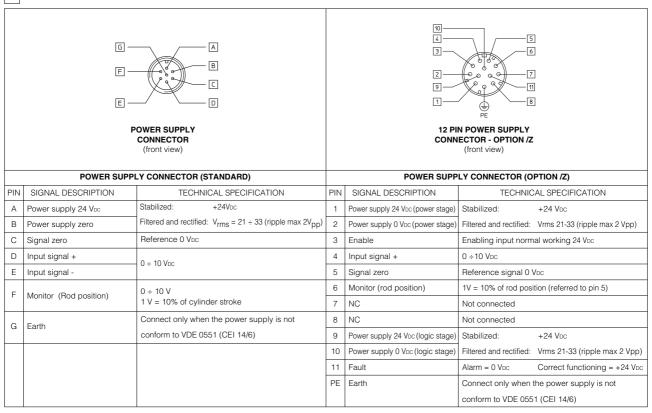
2 SERVOACTUATOR COMPOSITION

Servoactuator model code	Servo cylinder code	Servo proportional pilot valve code (see tab. F180)	
060810 CKZ-XL-NN-10-63/28*0012-A-PS/GP	07K0323 CKT/10-9-63/28*0012-A002 L	- 050321 DLHZO-TEZ-LN-PS-040-L51/B	
060810 CKZ-XL-NN-10-80/36*0012-A-PS/GP	06K0119 CKT/10-9-80/36*0012-A002 L		
060810 CKZ-XL-NN-10-100/45*0012-A-PS/GP	06K0120 CKT/10-9-100/45*0012-A002 L		
060810 CKZ-XL-NN-10-125/45*0012-A-PS/GP	06K0121 CKT/10-9-125/63*0012-A002 L		
060810 CKZ-XL-NN-10-160/70*0012-A-PS/GP	06K0219 CKT/20-9-160/70*0012-A002 L	- 060288 DLKZOR-TEZ-LN-PS-140-L31/B	
060810 CKZ-XL-NN-10-200/90*0012-A-PS/GP	T806532 CKT/20-9-200/90*0012-A002 L		

3 MAIN CHARACTERISTICS

Bore diameter [mm]		80	100	125	
Rod diameter [mm]		36	45	45	
Working stroke		[mm]	12		
Max pressure		[bar]	160		
Max force	(KN) -	Pull	64	100	170
		Push	80	125	190
Max speed		[m/s]	0,5		
Command signal		[VDC]	$0 \div 10$ (0V = rod fully in: standard) (0V = rod fully out: option /B)		
Linearity			0,03		
Response time at step signal (0-100%) [m/s]		115	300	320	

4 INTEGRAL DIGITAL ELECTRONICS WIRING



COMMUNICATION CONNECTOR			
Communication options PS (RS232)		PS (RS232) male connector	
1	1	NC	
		Not Connected	2 1
_		NC	
ţi	_	Not Connected	
mbe	descrip 8	RS_GND	
al de	Signal zero data line	5	
Pin Signal	RS_RX	COMMUNICATION	
		Valves receiving data line	(front view)
5	5	RS_TX	
	Valves transmitting data line		

5 MODEL CODE of power supply and communication connectors (to be ordered separately)

POWER SUPPLY CONNECTOR	COMMUNICATION CONNECTOR
SP-ZH-7P	SP-7H-5P
SP-ZH-12P (option /Z)	3F-ZN-3F

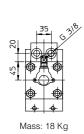
6 PROGRAMMING DEVICES

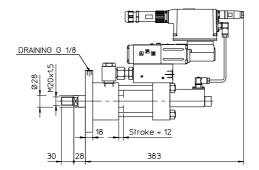
The functional parameters of the servoactuator, as the bias, scale, ramp and linearization of the regulation characteristic, can be easily set and optimized with graphic interface by using the following software programming devices suitable for standard PC:

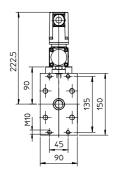
KIT-E-SW-PS for electronics with RS232 interface (option -PS) see tab. G500 for complete information about the programming device kits and for the PC minimum requirements.

The above programming devices have to be ordered separately.

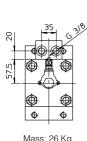
060810 CKZ-XL-NN-10-63/28*0012-A-PS-GP



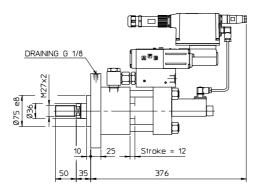


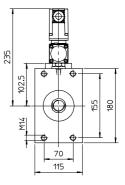


060810 CKZ-XL-NN-10-80/36*0012-A-PS-GP

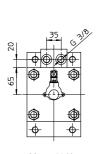




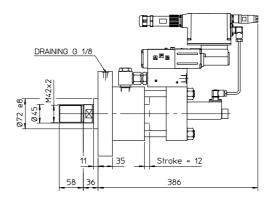


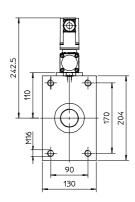


060810 CKZ-XL-NN-10-100/45*0012-A-PS-GP

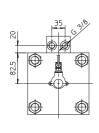


Mass: 36 Kg

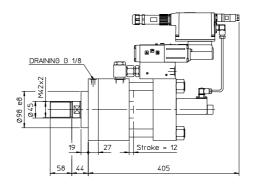


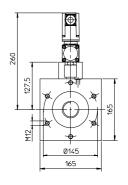


060810 CKZ-XL-NN-10-125/45*0012-A-PS-GP

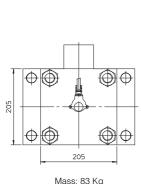




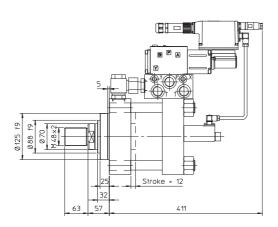


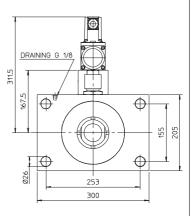


060810 CKZ-XL-NN-10-160/70*0012-A-PS-GP



Mass: 83 Kg





060810 CKZ-XL-NN-10-200/90*0012-A-PS-GP

